# Equations of geodesics in two dimensional Finsler space with special $(\alpha, \beta)$ - metric 

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#### Abstract

The equation of geodesic in a two-dimensional Finsler space is given by Matsumoto and Park for Finsler space with a $(\alpha, \beta)$-metric in the year 1997 and 1998. Further Park and Lee studied the above case for generalized Kropina metric in the year 2000. Recently Chaubey and his co-authors studied the same for some special $(\alpha, \beta)$ - metric in 2013 and 2014. In continuation of this the purpose of present paper is to express the differential equations of geodesics in a two-dimensional Finsler space with some special Finsler $(\alpha, \beta)$-metric.


Keywords: Finsler space, geodesic equations, $(\alpha, \beta)$ - metric, two dimensional Finsler space.

## 1 Introduction

In 1994,M. Matsumoto[6] studied the equation of geodesic in two dimensional Finsler spacesin detail. After that 1997, Matsumoto and Park[1] obtained the equation of geodesics in two dimensional Finsler spaces with the Randers metric $(L=\alpha+\beta)$ and the Kropina metric $L=\left(\frac{\alpha^{2}}{\beta}\right)$, and in 1998, they have [2] obtained the equation of geodesic in twodimensional Finsler space with the slope metrics, i.e. Matsumoto metric given by $L=\frac{\alpha^{2}}{(\alpha-\beta)}$, by considering $\beta$ as an infinitesimal of degree one and neglecting infinitesimal of degree more than two they obtained the equations of geodesic of two-dimensional Finsler space in the form $y^{\prime \prime}=f\left(x, y, y^{\prime}\right)$, where $(x, y)$ are the co-ordinate of two-dimensional Finsler space. Further Park and Lee [3] studied the above case for generalized Kropina metric in the year 2000. In continuation of this Chaubey and his co-authors $[7,8]$ are studied the same case for the different special $(\alpha, \beta)$-metric and illustrated their main results in the different figures. In the present paper we have shown that under the same conditions, the geodesic of the two-dimensional space with following metrics: $L=\alpha+\beta+\frac{\beta^{2}}{\alpha-\beta}, L=\alpha+\beta+\frac{\beta^{2}}{\alpha}+\frac{\beta^{3}}{\alpha^{2}}$, and $L=\alpha+\beta+\frac{\beta^{n+1}}{\alpha^{n}}$.

## 2 Preliminaries

Let $F^{2}=\left(M^{2}, L\right)$ be a two dimensional Finsler space with a Finslermetric function $L\left(x^{1}, x^{2} ; y^{1}, y^{2}\right)$. We denote $\frac{\partial f}{\partial x^{i}}=f_{i}, \frac{\partial f}{\partial y^{i}}=f_{(x)}(i=1,2)$ for any Finsler function $f\left(x^{1}, x^{2} ; y^{1}, y^{2}\right)$. Hereafter, the suffices $\mathrm{i}, \mathrm{j}$ run over $1,2$.

Since $L\left(x^{1}, x^{2} ; y^{1}, y^{2}\right)$ is (1) p-homogeneous in $\left(y^{1}, y^{2}\right)$ we have $L_{(j)(i)} y^{i}=0$ which imply the existence of a function, so called the Weierstrass invariant $W\left(x^{1}, x^{2} ; y^{1}, y^{2}\right)[1,2,8]$ given by

$$
\begin{equation*}
\frac{L_{(1)(1)}}{\left(y^{2}\right)^{2}}=-\frac{L_{(1)(2)}}{y^{1} y^{2}}=-\frac{L_{(2)(2)}}{\left(y^{1}\right)^{2}}=W\left(x^{1}, x^{2} ; y^{1}, y^{2}\right) \tag{1}
\end{equation*}
$$

[^0]In a two-dimensional associated Riemannian space $R^{2}=\left(M^{2}, \alpha\right)$ with respect to $L=\alpha$ and ? $\alpha^{2}=a_{i j}\left(x^{1}, x^{2}\right) y^{i} y^{j}$, the Weierstrass invariant $W_{r}$ of $R^{2}$ is written as

$$
W_{r}=\frac{1}{\alpha^{3}} a_{11} a_{22}-\left(a_{12}\right)^{2} .
$$

Further $L_{j}$ are still (l) p-homogeneous in $\left(y^{1}, y^{2}\right)$, so that we get

$$
\begin{equation*}
L_{j(i)} y^{i}=L_{j} . \tag{2}
\end{equation*}
$$

The geodesic equations in $F^{2}$ along curve $C: x^{i}=x^{i}(t)$ are given by [1].

$$
\begin{equation*}
L_{i}-\frac{d L_{i}}{d t}=0 \tag{3}
\end{equation*}
$$

Substituting (2) in (3), we get

$$
\begin{equation*}
L_{1(2)}-L_{2(1)}+\left(y^{1} \dot{y}^{2}-y^{2} \dot{y}^{1}\right) W=0 \tag{4}
\end{equation*}
$$

which is called the Weierstrass form of geodesic equation in $F^{2},[1,2]$ where $\dot{y}^{i}=d y^{i} / d t$.For the metric function $L(x, y ; \dot{x}, \dot{y})$ and (4) becomes to

$$
\begin{equation*}
\frac{\partial^{2} L}{\partial \dot{y} \partial x}-\frac{\partial^{2} L}{\partial \dot{x} \partial y}+(\ddot{x} \ddot{y}-\dot{y} \ddot{x}) \frac{\partial^{2} L}{(\partial \dot{y})^{2}}=0 . \tag{5}
\end{equation*}
$$

Let $\Gamma=\left\{\gamma_{j k}^{i}\left(x^{1}, x^{2}\right)\right\}$ be the Levi-Civita connection of the associated Riemannian space $R^{2}$. We introduce the linear Finsler connection $\Gamma=\left(\gamma_{j}^{i} k, \gamma_{0}^{i} j, 0\right)$ and the h- and c-covariant differentiation in $\Gamma^{*}$ are denoted by $(; i,(i))$ respectively, where the index (0) means the contraction with $y^{i}$. Then we have $y_{; j}^{i}=0, \alpha_{; i}=0$ and $\alpha_{(i) ; j}=0$.

## 3 Equation of Geodesics in a two dimensional Finsler with $(\alpha, \beta)$ - metric space

In [2,4,5] a two dimensional Finsler space $F^{2}=M^{2}, L(\alpha, \beta)$ with an $(\alpha, \beta)$ - metric, here $\beta=b_{i}\left(x^{1}, x^{2}\right) y^{i}$. For metric function $L(\alpha, \beta)$, we have

$$
\begin{equation*}
L_{(; i)}=L_{\beta} \beta_{;}, L_{(i)}=L_{\alpha} \alpha_{(i)}+L_{\beta} b_{(i)} \tag{6}
\end{equation*}
$$

where $\alpha_{(i)}=\frac{a_{i r y} y^{r}}{\alpha}$ and the subscriptions $\alpha, \beta$ of L are the partial derivatives of L with respect to $\alpha, \beta$ respectively. Then we have in $\Gamma^{*}$.

$$
L_{(j) ; i}=L_{(j) i}-L_{(j)(i)} \gamma_{0 i}^{r}-L_{r} \gamma_{j i}^{r}
$$

from which

$$
\begin{equation*}
L_{1(2)}-L_{2(1)}=L_{(2) ; 1}-L_{(1) ; 2}+L_{(2)(r)} \gamma_{(01)}^{r}-L_{(1)(r)} \gamma_{(02)}^{r} . \tag{7}
\end{equation*}
$$

From (1) and (7) we have

$$
\begin{equation*}
L_{1(2)}-L_{2(1)}=L_{(2) ; 1}-L_{(1) ; 2}+W\left(y^{1} \gamma_{00}^{2}-y^{2} \gamma_{00}^{1}\right) . \tag{8}
\end{equation*}
$$

On other hand, from (6) we have

$$
\begin{equation*}
L_{(j) ; i}=L_{\alpha \beta} \beta_{(; i)}(; i) \beta_{(j)}+L_{\beta \beta} \beta_{(; i)} b_{j} j+L_{\beta} \beta_{(; i)} b_{(j ; i)} . \tag{9}
\end{equation*}
$$

Similarly to the case of $L\left(x^{1} x^{2} ; y^{1} y^{2}\right)$ and $\alpha\left(x^{1}, x^{2}\right)$, we get the Weierstrass invariant $w(\alpha, \beta)$ as follows:

$$
\begin{equation*}
w=\frac{L_{\alpha \alpha}}{\beta^{2}}=-\frac{L_{\alpha \beta}}{\alpha \beta}=\frac{L_{\beta \beta}}{\alpha^{2}} . \tag{10}
\end{equation*}
$$

Substituting (10) in (9), we have

$$
\begin{equation*}
L_{(j) ; i}=\alpha w \beta_{; i}\left(\alpha b_{j}-\beta \alpha_{j}\right)+L_{\beta} b_{j ; i} \tag{11}
\end{equation*}
$$

From (8) and (11) we have

$$
\begin{equation*}
L_{1(2)}-L_{2(1)}=\alpha w\left\{\beta_{; 1}\left(\alpha b_{2}-\beta \alpha_{(2)}\right)-\beta_{; 2}\left(\alpha b_{1}-\beta \alpha_{(1)}\right)\right\}-L_{\beta}\left(L_{(1 ; 2)}-L_{(2 ; 1)}\right)+W\left(y^{1} \gamma_{00}^{2}-y^{2} \gamma_{00}^{1}\right) \tag{12}
\end{equation*}
$$

If we put $y_{; 0}^{i}=\dot{y}^{i}+\gamma_{00}^{i}$, we get

$$
\begin{equation*}
y^{1} \dot{y}^{2}-y^{2} \dot{y}^{1}=y^{1} y_{; 0}^{2}-y^{2} y_{; 0}^{1}-\left(y^{1} \gamma_{00}^{2}-y^{2} \gamma_{00}^{1}\right) . \tag{13}
\end{equation*}
$$

Substituting (12) and (13) in (4), we have

$$
\begin{equation*}
\alpha w\left\{\beta_{; 1}\left(\alpha b_{2}-\beta \alpha_{(2)}\right)-\beta_{; 2}\left(\alpha b_{1}-\beta \alpha_{(1)}\right)\right\}-L_{\beta}\left(\frac{\partial b_{1}}{\partial x^{2}}-\frac{\partial b_{2}}{\partial x^{1}}\right)+W\left(y^{1} y_{; 0}^{2}-y^{2} y_{; 0}^{1}\right)=0 \tag{14}
\end{equation*}
$$

where $\beta_{; i}=b_{r ; i} y^{r}$. The relation of $\mathrm{W}, W_{r}$ and w is written as follows:

$$
\begin{equation*}
W=\left(L_{\alpha}+\alpha w \gamma^{2}\right) W_{r} \tag{15}
\end{equation*}
$$

where $\gamma^{2}=b^{2} \alpha^{2}-\beta^{2}$ and $b^{2}=a^{i j} b_{i} b_{j}$. Therefore (14) is expressed as follows:

$$
\begin{equation*}
\left(L_{\alpha}+\alpha w \gamma^{2}\right)\left(y^{1} y_{; 0}^{2}-y^{2} y_{; 0}^{1}\right) W_{r}-L_{\beta}\left(\frac{\partial b_{1}}{\partial x^{2}}-\frac{\partial b_{2}}{\partial x^{1}}\right)+\alpha w\left\{b_{0 ; 1}\left(\alpha b_{2}-\beta \alpha_{(2)}\right)-b_{0 ; 2}\left(\alpha b_{1}-\beta \alpha_{(1)}\right)\right\}=0 \tag{16}
\end{equation*}
$$

Thus we have the following.
Theorem 1. In a two-dimensional Finsler space $F^{2}$ with an $(\alpha, \beta)-$ metric, the differential equation of a geodesic is given by (16).

Suppose that $\alpha$ be positive-definite. Then we may refer to an isothermal coordinate system $\left(x^{i}\right)=(x, y)([1,2])$ such that

$$
\alpha=a E, a=a(x, y)>0, E=\sqrt{\dot{x}^{2}+\dot{y}^{2}},
$$

that is $a_{11}=a_{22}=a^{2}, a_{12}=0$ and $\left(y^{1}, y^{2}\right)=(\dot{x}, \dot{y})$. From $\alpha^{2}=a_{i j}(x) y^{i} y^{j}$ we get $\alpha \alpha_{(i)(j)}=a_{i j}-a_{i r} a_{j s} \frac{y^{r} y^{s}}{\alpha^{2}}$. Therefore we have $\alpha \alpha_{(1)(1)}=\left(\frac{a \dot{y}}{E}\right)^{2}$ and $W_{r}=\frac{a}{E^{3}}$. Furthermore the Christoffel symbols are given by

$$
\gamma_{11}^{1}=-\gamma_{22}^{1}=\gamma_{12}^{2}=\frac{a_{x}}{a}, \gamma_{12}^{1}=-\gamma_{11}^{2}=\gamma_{22}^{2}=\frac{a_{y}}{a},
$$

where $a_{x}=\frac{\partial a}{\partial x}, a_{y}=\frac{\partial a}{\partial y}$. Therefore we have

$$
\begin{equation*}
\left(y^{1} y_{; 0}^{2}-y^{2} y_{; 0}^{1}\right) W_{r}=\frac{a}{E^{3}}(\ddot{x} \ddot{y}-\ddot{y} \ddot{x})+\frac{1}{E}\left(a_{x} \dot{y}-a_{y} \dot{x}\right) \tag{17}
\end{equation*}
$$

Next calculating $\gamma^{2}=b^{2} \alpha^{2}-\beta^{2}, b_{0 ; 1}\left(\alpha b_{2}-\beta \alpha_{(2)}\right)$ and $b_{0 ; 2}\left(\alpha b_{1}-\beta \alpha_{(1)}\right)$ we have

$$
\begin{gather*}
\gamma^{2}=\left(b_{1}\right)^{2}+\left(b_{2}\right)^{2}\left(\dot{x}^{2}+\dot{y}^{2}\right)-\left(b_{1} \dot{x}+b_{2} \dot{y}\right)^{2}=\left(b_{1} \dot{y}-b_{2} \dot{x}\right)^{2},  \tag{18}\\
b_{r ; 1}\left(\alpha b_{2}-\beta \alpha_{(2)}\right) y^{r}=\frac{a}{E} b_{0 ; 1}\left(b_{2} \dot{y}-b_{1} \dot{x}\right) \dot{x}  \tag{19}\\
b_{r ; 2}\left(\alpha b_{1}-\beta \alpha_{(1)}\right) y^{r}=\frac{a}{E} b_{0 ; 2}\left(b_{1} \dot{y}-b_{2} \dot{x}\right) \dot{y} . \tag{20}
\end{gather*}
$$

Substituting (17), (18), (19) and (20) in (16), we have

$$
\begin{equation*}
\left\{a(\ddot{x} \ddot{y}-\ddot{y} \ddot{x})+E^{2}\left(a_{x} \dot{y}-a_{y} \dot{x}\right)\right\}\left\{L \alpha+a E w\left(b_{1} \dot{y}-b_{2} \dot{x}\right)^{2}\right\}-E^{3} L_{\beta}\left(b_{1 y}-b_{2 x}\right)-E^{3} a^{2} w\left(b_{1 \dot{y}}-b_{2 \dot{x}}\right) b_{0 ; 0}=0 \tag{21}
\end{equation*}
$$

where

$$
\begin{equation*}
b_{0 ; 0}=b_{r} s y^{r} y^{s}=\left(b_{1 x} \dot{x}+b_{1 y} \dot{y}\right) \dot{x}+\left(b_{2 x} \dot{x}+b_{2 y} \dot{y}\right)+\frac{1}{a}\left\{\left(\dot{x}^{2}+\dot{y}^{2}\right)\left(a_{x} b_{1}+a_{y} b_{2}\right)-2\left(b_{1} \dot{x}+b_{2} \dot{y}\right)\left(a_{x} \dot{x}+a_{y} \dot{y}\right)\right\} \tag{22}
\end{equation*}
$$

where $b_{i x}=\frac{\partial b_{i}}{\partial x}$ and $b_{i y}=\frac{\partial b_{i}}{\partial y}$. Thus we have the following.
Theorem 2. In a two dimensional Finsler space $F^{2}$ with an $(\alpha, \beta)$ - metric, if we refer to an isothermal coordinate system $(x, y)$ such that $\alpha=a E$, then the differential equation of a geodesic is given by (21) and (22).

## 4 Equation of Geodesics in a two dimensional Finsler with special $(\alpha, \beta)$-metric

$L=\alpha+\beta+\frac{\beta^{2}}{(\alpha-\beta)}$
The $(\alpha, \beta)$-metric $L(\alpha, \beta)=\alpha+\beta+\frac{\beta^{2}}{(\alpha-\beta)}$ is called special $(\alpha, \beta)$ metric

$$
\begin{align*}
L_{\alpha} & =1-\frac{\beta^{2}}{(\alpha-\beta)^{2}}, \quad L_{\alpha \alpha}=\frac{2 \beta^{2}}{(\alpha-\beta)^{3}}  \tag{23}\\
L_{\alpha \beta} & =-\frac{\alpha \beta}{(\alpha-\beta)^{3}}, \quad L_{\beta \beta}=\frac{2 \alpha^{2}}{(\alpha-\beta)^{3}} \\
w & =\frac{L_{\alpha \alpha}}{\beta^{2}}=-\frac{L_{\alpha \beta}}{\alpha \beta}=\frac{L_{\beta \beta}}{\alpha^{2}}=\frac{2}{(\alpha-\beta)^{3}} .
\end{align*}
$$

Substituting (23) in (21), we obtain the differential equation of a geodesic in an isothermal coordinate system (x,y) with respect to $\alpha$ as follows:

$$
\begin{align*}
& \left\{\alpha(\alpha-\beta)(\alpha-2 \beta)+2 \alpha\left(b_{1} \dot{y}-b_{2} \dot{x}\right)^{2}\right\}\left\{a(\dot{x} \ddot{y}-\ddot{y} \ddot{x})+E^{2}\left(a_{x} \dot{y}-a_{y} \dot{x}\right)\right\}-E^{3} \alpha^{2}(\alpha-\beta)\left(b_{1 y}-b_{2 x}\right)  \tag{24}\\
& \quad-2 E^{3} a^{2}\left(b_{1} \dot{y}-b_{2} \dot{x}\right) b_{0 ; 0}=0 .
\end{align*}
$$

In the particular case for the t of curve C is chosen x of $(x, y)$, then $\dot{x}=1, \dot{y}=y^{\prime}, \ddot{x}=0, \ddot{y}=y^{\prime \prime}, E=\sqrt{1+\left(y^{\prime}\right)^{2}}$.

$$
\begin{align*}
& \left\{\alpha(\alpha-\beta)(\alpha-2 \beta)+2 \alpha\left(b_{1} y^{\prime}-b_{2}\right)^{2}\right\}\left\{a y^{\prime \prime}+\left(1+\left(y^{\prime}\right)^{2}\right)\left(a_{x} y^{\prime}-a_{y}\right)\right\}-a\left(1+\left(y^{\prime}\right)^{2}\right)\left\{\left(1+\left(y^{\prime}\right)^{2}\right)\right.  \tag{25}\\
& \left.\quad \alpha(\alpha-\beta)\left(b_{1 y}-b_{2 x}\right)-2 \alpha\left(b_{1} y^{\prime}-b_{2}\right) b_{0 ; 0}\right\}=0 \\
&  \tag{26}\\
& b_{0 ; 0}^{*}=\left(b_{1 x}+b_{1 y} y^{\prime}\right)+\left(b_{2 x}+b_{2 y} y^{\prime}\right) y^{\prime}+\frac{1}{a}\left\{\left(1+\left(y^{\prime}\right)^{2}\right)\left(a_{x} b_{1}+a_{y} b_{2}\right)-2\left(b_{1}+b_{2} y^{\prime}\right)\left(a_{x}+a_{y} y^{\prime}\right)\right\} .
\end{align*}
$$

It seems quite complicated from, but $y^{\prime \prime}$ is given as a fractional expression in $y^{\prime}$. Thus we have the following
Theorem 3. Let $F^{2}$ be two-dimensional space with special Finsler metric. If we refer to a local coordinate system $(x, y)$ with respect to $\alpha$, then the differential equation of a geodesic $y=y(x)$ of $F^{2}$ is of the form

$$
y^{\prime \prime}=\frac{g\left(x, y, y^{\prime}\right)}{f\left(x, y, y^{\prime}\right)}
$$

where $f\left(x, y, y^{\prime}\right)$ is a quadratic polynomial in $y^{\prime}$ and $g\left(x, y, y^{\prime}\right)$ is a polynomial in $y^{\prime}$ of degree at most five.
In order to find the concrete form, we treat the case of which the associated Riemannian space is Euclidean with orthonormal coordinate system. Then $a=1$ and $a_{x}=a_{y}=0$. If we take scalar function b such that $b_{1}=b_{x}, b_{2}=b_{y}$ then $b_{1 y}-b_{2 x}=0$.therefore (25) is reduces to

$$
\begin{equation*}
y^{\prime \prime}=\frac{\left(-2 \alpha\left\{1+\left(y^{\prime}\right)^{2}\right)\right\}\left(b_{x} y^{\prime}-b_{y}\right)\left(b_{1 x}+b_{2 y} y^{\prime}\right)\left(b_{2 x}+b_{2 y} y^{\prime}\right) y^{\prime}}{\left\{\alpha(\alpha-\beta)(\alpha-2 \beta)+2 \alpha\left(b_{1} y^{\prime}-b_{2}\right)^{2}\right\}} \tag{27}
\end{equation*}
$$

Thus we have the following
Corollary 1. Let $F^{2}$ be a two -dimensional Finsler space with a special metric. If we refer to an orthonormal coordinate system $(x, y)$ with respect to $\alpha$ and $b_{1}=\frac{\partial b}{\partial x}, b_{2}=\frac{\partial b}{\partial y}$ for a scalar $b$, then the differential space of geodesic $y=y(x)$ of $F^{2}$ is given by (27).

## 5 Equation of Geodesics in a two dimensional Finsler with special $(\alpha, \beta)$-metric

$L=\alpha+\beta+\frac{\alpha^{2}}{\beta}+\frac{\alpha^{3}}{\beta^{2}}$
The $(\alpha, \beta)$-metric $L(\alpha, \beta)=\alpha+\beta+\frac{\alpha^{2}}{\beta}+\frac{\alpha^{3}}{\beta^{2}}$ is called special $(\alpha, \beta)$ metric

$$
\begin{align*}
L_{\alpha} & =1+\frac{2 \alpha}{\beta}+\frac{3 \alpha^{2}}{\beta^{2}}, L_{\alpha \alpha}=\frac{2}{\beta}+\frac{6 \alpha}{\beta^{2}}, L_{\beta}=1-\frac{\alpha^{2}}{\beta^{2}}-\frac{2 \alpha^{2}}{\beta^{3}}  \tag{28}\\
L_{\beta \beta} & =\frac{2 \alpha^{2}}{\beta^{3}}+\frac{6 \alpha^{3}}{\beta^{4}}, L_{\alpha \beta}=-\frac{\alpha(2 \beta+6 \alpha)}{\beta^{3}}, \\
w & =\frac{L_{\alpha \alpha}}{\beta^{2}}=-\frac{L_{\alpha \beta}}{\alpha \beta}=\frac{L_{\beta \beta}}{\alpha^{2}}=\frac{\beta+6 \alpha}{\beta^{4}} .
\end{align*}
$$

Substituting (28) in (21), we obtain the differential equation of a geodesic in an isothermal coordinate system ( $\mathrm{x}, \mathrm{y}$ ) with respect to $\alpha$ as follows:

$$
\begin{array}{r}
\left\{\beta^{2}\left(\beta^{2}+2 \alpha \beta\right)+\alpha(2 \beta+6 \alpha)\left(b_{1} \dot{y}-b_{2} \dot{x}\right)^{2}\right\}\left\{a(\dot{x} \ddot{y}-\ddot{y} \ddot{x})+E^{2}\left(a_{x} \dot{y}-a_{y} \dot{x}\right)\right\}-E^{3} \beta\left(\beta^{3}-3 \alpha^{2} \beta-2 \alpha^{3}\right)\left(b_{1 y}-b_{2 x}\right)  \tag{29}\\
-E^{3} a^{2}(2 \beta+6 \alpha)\left(b_{1} \dot{y}-b_{2} \dot{x}\right) b_{0 ; 0}=0
\end{array}
$$

In the particular case for the t of curve C is chosen x of $(x, y)$, then $\dot{x}=1, \dot{y}=y^{\prime}, \ddot{x}=0, \ddot{y}=y^{\prime \prime}, E=\sqrt{1+\left(y^{\prime}\right)^{2}}$.

$$
\begin{align*}
&\left\{\beta^{2}\left(\beta^{2}+2 \alpha \beta\right)+\alpha(2 \beta+6 \alpha)\left(b_{1} y^{\prime}-b_{2}\right)^{2}\right\}\left\{a y^{\prime \prime}+\left(1+\left(y^{\prime}\right)^{2}\right)\left(a_{x} y^{\prime}-a_{y}\right)\right\}-a\left(1+\left(y^{\prime}\right)^{2}\right)\left(\left\{\left(1+\left(y^{\prime}\right)^{2}\right) \beta\right.\right.  \tag{30}\\
&\left.\left(\beta^{3}-3 \alpha^{2} \beta-2 \alpha^{3}\right)\left(b_{1 y}-b_{2 x}\right)+\alpha(2 \beta+6 \alpha)\left(b_{1} y^{\prime}-b_{2}\right) b_{0 ; 0}=0\right) \\
& b_{0 ; 0}^{*}=\left(b_{1 x}+b_{1 y} y^{\prime}\right)+\left(b_{2 x}+b_{2 y} y^{\prime}\right) y^{\prime}+\frac{1}{a}\left\{\left(1+\left(y^{\prime}\right)^{2}\right)\left(a_{x} b_{1}+a_{y} b_{2}\right)-2\left(b_{1}+b_{2} y^{\prime}\right)\left(a_{x}+a_{y} y^{\prime}\right)\right\} \tag{31}
\end{align*}
$$

It seems quite complicated from, buty ${ }^{\prime \prime}$ is given as a fractional expression in $y^{\prime}$. Thus we have the following.
Theorem 4. Let $F^{2}$ be two-dimensional space with special Finsler metric. If we refer to a local coordinate system ( $x, y$ ) with respect to $\alpha$, then the differential equation of a geodesicy $=y(x)$ of $F^{2}$ is of the form

$$
y^{\prime \prime}=\frac{g\left(x, y, y^{\prime}\right)}{f\left(x, y, y^{\prime}\right)}
$$

where $f\left(x, y, y^{\prime}\right)$ is a quadratic polynomial in $y^{\prime}$ and $g\left(x, y, y^{\prime}\right)$ is a polynomial in $y^{\prime}$ of degree at most five.

In order to find the concrete form, we treat the case of which the associated Riemannian space is Euclidean with orthonormal coordinate system. Then $a=1$ and $a_{x}=a_{y}=0$. If we take scalar function b such that $b_{1}=b_{x}, b_{2}=b_{y}$ then $b_{1 y}-b_{2 x}=0$.Therefore (30) is reduces to

$$
\begin{equation*}
y^{\prime \prime}=\frac{(6 \alpha+2 \beta) \alpha\left(1+\left(y^{\prime}\right)^{2}\right)\left(b_{x} y^{\prime}-b_{y}\right)\left(b_{1 x}+b_{2 y} y^{\prime}\right)\left(b_{2 x}+b_{2 y} y^{\prime}\right) y^{\prime}}{\beta^{2}\left(\beta^{2}+2 \alpha \beta+3 \alpha^{2}\right)+\alpha(2 \beta+6 \alpha)\left(b_{1} y^{\prime}-b_{2}\right)^{2}} . \tag{32}
\end{equation*}
$$

Thus we have the following.
Corollary 2. Let $F^{2}$ be a two -dimensional Finsler space with a special metric. If we refer to an orthonormal coordinate system $(x, y)$ with respect to $\alpha$ and $b_{1}=\frac{\partial b}{\partial x}, b_{2}=\frac{\partial b}{\partial y}$ for a scalar $b$, then the differential space of geodesic $y=y(x)$ of $F^{2}$ is given by (32).

## 6 Equation of Geodesics in a two dimensional Finsler with special $(\alpha, \beta)$-metric

$L=\alpha+\beta+\frac{\beta^{(n+1)}}{\alpha^{n}}$
The $(\alpha, \beta)$-metric $L(\alpha, \beta)=\alpha+\beta+\frac{\beta^{(n+1)}}{\alpha^{n}}$ is called special $(\alpha, \beta)$ metric.

$$
\begin{align*}
L_{\alpha} & =1-n \frac{\beta^{(n+1)}}{\alpha(n+1)}, \quad L_{\alpha \alpha}=n(n+1) \frac{\beta^{(n+1)}}{\alpha^{(n+2)}},  \tag{33}\\
L_{\beta} & =1+(n+1) \frac{\beta^{n}}{\alpha^{n}}, \quad L_{\beta \beta}=n(n+1) \frac{\beta^{(n-1)}}{\alpha^{n}}, \\
L_{\alpha \beta} & =-n(n+1) \frac{\beta^{n}}{\alpha^{(n+1)}}, \\
w & =\frac{L_{\alpha \alpha}}{\beta^{2}}=-\frac{L_{\alpha \beta}}{\alpha \beta}=\frac{L_{\beta \beta}}{\alpha^{2}}=n(n+1) \frac{\beta^{(n-1)}}{\alpha^{(n+2)}} .
\end{align*}
$$

Substituting (33) in (21), we obtain the differential equation of a geodesic in an isothermal coordinate system ( $\mathrm{x}, \mathrm{y}$ ) with respect to $\alpha$ as follows:

$$
\begin{align*}
& \quad\left\{\left(\alpha^{(n+1)}-n \beta^{(n+1)}\right)+n(n+1) \beta^{(n-1)}\left(b_{1} \dot{y}-b_{2} \dot{x}\right)^{2}\right\}\left\{a(\ddot{x} \ddot{y}-\ddot{y} \ddot{x})+E^{2}\left(a_{x} \dot{y}-a_{y} \dot{x}\right)\right\}  \tag{34}\\
& -E^{3} \alpha\left(\alpha^{n}+(n+1) \beta^{n}\right)\left(b_{1 y}-b_{2 x}\right)-E^{3} a^{2} n(n+1) \beta^{(n-1)}\left(b_{1} \dot{y}-b_{2} \dot{x}\right) b_{0 ; 0}=0 .
\end{align*}
$$

In the particular case for the t of curve C is chosen x of $(x, y)$, then $\dot{x}=1, \dot{y}=y^{\prime}, \ddot{x}=0, \ddot{y}=y^{\prime \prime}, E=\sqrt{1+\left(y^{\prime}\right)^{2}}$.

$$
\begin{align*}
&\left.\left.\left\{\left(\alpha^{( } n+1\right)-n \beta^{\prime} n+1\right)\right)+n(n+1) \beta^{( } n-1\right)\left.\left(b_{1} y^{\prime}-b_{2}\right)^{2}\right\}\left(a y^{\prime \prime}+\left(1+\left(y^{\prime}\right)^{2}\right)\left(a_{x} y^{\prime}-a_{y}\right)\right)-a\left(1+\left(y^{\prime}\right)^{2}\right)\left(\left(1+\left(y^{\prime}\right)^{2}\right)\right.  \tag{35}\\
&\left.\left.\left.\left(\alpha^{n}+(n+1) \beta^{n}\right)\right)\left(b_{1 y}-b_{2 x}\right)+n(n+1) \beta^{( } n-1\right)\left(b_{1} y^{\prime}-b_{2}\right) b_{0 ; 0}=0\right) \\
& b_{0 ; 0}^{*}=\left(b_{1 x}+b_{1 y} y^{\prime}\right)+\left(b_{2 x}+b_{2 y} y^{\prime}\right) y^{\prime}+\frac{1}{a}\left(\left(1+\left(y^{\prime}\right)^{2}\right)\left(a_{x} b_{1}+a_{y} b_{2}\right)-2\left(b_{1}+b_{2} y^{\prime}\right)\left(a_{x}+a_{y} y^{\prime}\right)\right) . \tag{36}
\end{align*}
$$

It seems quite complicated from, buty" is given as a fractional expression in $y^{\prime}$. Thus we have the following,
Theorem 5. Let $F^{2}$ be two-dimensional space with special Finsler metric. If we refer to a local coordinate system $(x, y)$ with respect to $\alpha$, then the differential equation of a geodesicy $=y(x)$ of $F^{2}$ is of the form

$$
y^{\prime \prime}=\frac{g\left(x, y, y^{\prime}\right)}{f\left(x, y, y^{\prime}\right)},
$$

where $f\left(x, y, y^{\prime}\right)$ is a quadratic polynomial in $y^{\prime}$ and $g\left(x, y, y^{\prime}\right)$ is a polynomial in $y^{\prime}$ of degree at most five.
In order to find the concrete form, we treat the case of which the associated Riemannian space is Euclidean with orthonormal coordinate system. Then $a=1$ and $a_{x}=a_{y}=0$. If we take scalar function b such that $b_{1}=b_{x}, b_{2}=b_{y}$ then $b_{1 y}-b_{2 x}=0$.Therefore (35) is reduces to

$$
\begin{equation*}
y^{\prime \prime}=\frac{n(n+1) \beta^{(n-1)\left(1+\left(y^{\prime}\right)^{2}\right)\left(b_{x} y^{\prime}-b_{y}\right)\left(b_{1 x}+b_{2 y} y^{\prime}\right)\left(b_{2 x}+b_{2 y} y^{\prime}\right) y^{\prime}}}{\left(\alpha^{(n+1)}-n \beta^{(n+1)}\right)+n(n+1) \beta^{(n-1)}\left(b_{1} y^{\prime}-b_{2}\right)^{2}} \tag{37}
\end{equation*}
$$

Thus we have the following.
Corollary 3. Let $F^{2}$ be a two-dimensional Finsler space with a special metric. If we refer to an orthonormal coordinate system $(x, y)$ with respect to $\alpha$ and $b_{1}=\frac{\partial b}{\partial x}, b_{2}=\frac{\partial b}{\partial y}$ for a scalar $b$, then the differential space of geodesic $y=y(x)$ of $F^{2}$ is given by (37).

## Competing interests

The authors declare that they have no competing interests.

## Authors' contributions

All authors have contributed to all parts of the article. All authors read and approved the final manuscript.

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