

Bright and dark soliton solution of the nonlinear partial differential equations system

Ozkan Guner

Cankiri Karatekin University, Faculty of Economics and Administrative Sciences, Department of International Trade, Cankiri-Turkey

Received: 25 April 2015, Revised: 1 May 2015, Accepted: 4 May 2015 Published online: 12 December 2015.

Abstract: In this paper, we obtained the 1-soliton solutions of the (3+1)-dimensional Zakharov–Kuznetsov (ZK) equation and the Drinfeld-Sokolov equation system. By using a solitary wave ansatz method, we obtain exact bright and dark soliton solutions for these equations. The parameters of the soliton envelope (amplitude, widths, velocity) are obtained as function of the dependent model coefficients. Note that, it is always useful and desirable to construct exact solutions especially soliton-type envelope for the understanding of most nonlinear physical phenomena.

Keywords: Exact solution, dark and bright soliton, the (3+1)dimensional Zakharov Kuznetsov (ZK) equation, Drinfeld-Sokolov equation system.

1 Introduction

In recent years, nonlinear waves is a very important topic of research in nonlinear dynamics, mathematical physics and various fields [1,2,3]. These wave equations are observed in fluid dynamics, aeronautics, optical fibers, solid state physics, plasma physics, chemical physics, geophysical sciences and geochemistry.

In the past decades, new exact solutions may help to find new phenomena. A variety of powerfull methods, such as the Jacobi elliptic function method [4,5], tanh-sech method [6,7], extended tanh method [8,9], $\left(\frac{G'}{G}\right)$ -expansion method [10, 11], homogeneous balance method [12,13], sine-cosine method [14,15,16], first integral method [17,18] and F-expansion method [19,20] were used to obtain the solitary wave solutions.

The solitary wave ansatz method was first proposed by Biswas [21] and Triki et al. [22] is particularly notable in its power and applicability in solving nonlinear problems, and it has been successfully applied to many kinds of nonlinear partial differential equations [23, 24]

2 The (3+1)-dimensional Zakharov–Kuznetsov (ZK) Equation

The Zakharov–Kuznetsov (ZK) equation governs the behavior of weakly nonlinear ion-acoustic waves in a plasma comprising cold ions and hot isothermal electrons in the presence of a uniform magnetic field. We considered the following ZK equation given by [25]

$$u_t + auu_x + (u_{xx} + u_{yy} + u_{zz})_x = 0, (1)$$

© 2015 BISKA Bilisim Technology



which is a typical nonlinear evolution equation, where a is real constants. Wazwaz constructed some new exact solutions by sine-cosine method in [26]. Wu and Fan obtained compactons, solitary patterns, plane periodic and solitary traveling wave solutions for Eq. (1), and their analytic expressions in [27].

Now, the bright soliton solution, dark soliton solution and conservation laws of this equation will be obtained.

2.1 The bright (non-topological) soliton solution:

To obtain the bright soliton solution of equation (1), the solitary wave ansatz admits the use of the assumption [28,29],

$$u(x, y, z, t) = \lambda sech^p \tau, \tag{2}$$

where $\tau = \eta (x + y + bz - vt)$ which λ , η and v are constant coefficients. Here λ is the amplitude, η and b are the inverse width and v is the velocity of the soliton. The exponents p is unknown at this point and will be determined later. From the ansatz (2), we obtain:

$$u_t = p\lambda\eta vsech^p\tau \tanh\tau, \tag{3}$$

$$uu_x = -\lambda^2 p\eta \operatorname{sech}^{2p} \tau \tanh \tau, \tag{4}$$

$$u_{xxx} = -p^3 \lambda \eta^3 \operatorname{sech}^p \tau \tanh \tau + p(p+1)(p+2)\lambda \eta^3 \operatorname{sech}^{p+2} \tau \tanh \tau,$$
(5)

$$u_{yyx} = -p^3 \lambda \eta^3 \operatorname{sech}^p \tau \tanh \tau + p(p+1)(p+2)\lambda \eta^3 \operatorname{sech}^{p+2} \tau \tanh \tau, \tag{6}$$

$$u_{zzx} = -p^3 \lambda \eta^3 b^2 sech^p \tau \tanh \tau + p(p+1)(p+2)\lambda \eta^3 b^2 sech^{p+2} \tau \tanh \tau.$$
(7)

Substituting Eqs. (2)-(7) into Eq. (1), we get

$$p\lambda\eta vsech^{p}\tau \tanh\tau - a\lambda^{2}p\eta sech^{2p}\tau \tanh\tau - p^{3}\lambda\eta^{3}sech^{p}\tau \tanh\tau + p(p+1)(p+2)\lambda\eta^{3}sech^{p+2}\tau \tanh\tau - p^{3}\lambda\eta^{3}sech^{p}\tau \tanh\tau + p(p+1)(p+2)\lambda\eta^{3}sech^{p+2}\tau \tanh\tau - p^{3}\lambda\eta^{3}b^{2}sech^{p}\tau \tanh\tau$$

$$+ p(p+1)(p+2)\lambda\eta^{3}b^{2}sech^{p+2}\tau \tanh\tau = 0.$$
(8)

Equating the exponents of $sech^{2p}\tau \tanh \tau$ and $sech^{p+2}\tau \tanh \tau$ term in equation (8), one yields

$$2p = p + 2, (9)$$

which implies

$$p = 2. \tag{10}$$

We next equate the exponents of $sech^{2p}\tau \tanh \tau$ and $sech^{p+2}\tau \tanh \tau$ terms to zero one gets

$$-a\lambda^2 p\eta + p(p+1)(p+2)\lambda\eta^3 + p(p+1)(p+2)\lambda\eta^3 + p(p+1)(p+2)\lambda\eta^3 b^2 = 0.$$
 (11)

If we put p = 2 and solving the equation (11), the velocity of soliton is given by

$$\lambda = \frac{12\eta^2(2+b^2)}{a}, \ a \neq 0.$$
 (12)

156

By setting the coefficients of $\lim sech^p \tau$ terms in Eq. (8) to zero yields

$$p\lambda\eta v - 2p^3\lambda\eta^3 - p^3\lambda\eta^3b^2 = 0.$$
(13)

If we put p = 2 and solving the equation (13)

$$v = 4\eta^2 (2+b^2). \tag{14}$$

which gives the velocity of the soliton.

Finally, we get the bright (non topological) soliton solution for the constant coefficient the (3+1)-dimensional ZK equation, when the above expressions of p, v and λ given by Eqs. (10), (12) and (14) are substituted in (2) as :

$$u(x, y, z, t) = \lambda \lim \operatorname{sech}^2 \eta (x + y + bz - vt).$$
(15)

2.2 The dark (topological) soliton solution:

In this section, the ansatz method [30] will be used to carry out the integration of the (3+1)-dimensional ZK equation (1). The search is going to be for a dark soliton solution. We use an ansatz solution of the form [31,32,33]

$$u(x, y, z, t) = \lambda \tanh^p \tau, \tag{16}$$

and

$$\tau = \eta (x + y + bz - vt), \tag{2.17}$$

where λ , b and η are unknown free parameters and v is the velocity of the soliton, respectively, that will be determined.

The exponent p is also unknown.

From Eq. (16), we have:

$$u_t = -p\lambda v\eta \left\{ \tanh^{p-1} \tau - \tanh^{p+1} \tau \right\},\tag{17}$$

$$uu_{x} = p\lambda^{2}\eta \left\{ \tanh^{2p-1}\tau - \tanh^{2p+1}\tau \right\},$$
(18)

$$u_{xxx} = \lambda p \eta^{3} \left\{ \begin{array}{l} (p-1)(p-2) \tanh^{p-3} \tau - \left[2p^{2} + (p-1)(p-2)\right] \tanh^{p-1} \tau \\ + \left[2p^{2} + (p+1)(p+2)\right] \tanh^{p+1} \tau - (p+1)(p+2) \tanh^{p+3} \tau \end{array} \right\},$$
(19)

$$u_{yyx} = \lambda p \eta^{3} \left\{ \begin{array}{l} (p-1)(p-2) \tanh^{p-3} \tau - \left[2p^{2} + (p-1)(p-2)\right] \tanh^{p-1} \tau \\ + \left[2p^{2} + (p+1)(p+2)\right] \tanh^{p+1} \tau - (p+1)(p+2) \tanh^{p+3} \tau \end{array} \right\},$$
(20)

© 2015 BISKA Bilisim Technology



$$u_{zzx} = \lambda p \eta^{3} b^{2} \left\{ \begin{array}{l} (p-1)(p-2) \tanh^{p-3} \tau - \left[2p^{2} + (p-1)(p-2)\right] \tanh^{p-1} \tau \\ + \left[2p^{2} + (p+1)(p+2)\right] \tanh^{p+1} \tau - (p+1)(p+2) \tanh^{p+3} \tau \end{array} \right\},$$
(21)

where $\tau = \eta (x + y + bz - vt)$. Substituting Eqs. (17)-(21) into Eq. (1), we obtain

$$-p\lambda\nu\eta \left\{ \tanh^{p-1}\tau - \tanh^{p+1}\tau \right\} + ap\lambda^{2}\eta \left\{ \tanh^{2p-1}\tau - \tanh^{2p+1}\tau \right\}$$
(22)
+2 $\lambda p\eta^{3} \left\{ \begin{array}{c} (p-1)(p-2)\tanh^{p-3}\tau - [2p^{2} + (p-1)(p-2)]\tanh^{p-1}\tau \\ + [2p^{2} + (p+1)(p+2)]\tanh^{p+1}\tau - (p+1)(p+2)\tanh^{p+3}\tau \end{array} \right\}$ (22)
+ $\lambda p\eta^{3}b^{2} \left\{ \begin{array}{c} (p-1)(p-2)\tanh^{p-3}\tau - [2p^{2} + (p-1)(p-2)]\tanh^{p-1}\tau \\ + [2p^{2} + (p+1)(p+2)]\tanh^{p+1}\tau - (p+1)(p+2)\tanh^{p+3}\tau \end{array} \right\}$ = 0.

By equating the highest exponents of $\tanh^{2p+1} \tau$ and $\tanh^{p+3} \tau$ terms in Eq (22), one gets:

$$2p + 1 = p + 3, (23)$$

so that

$$p = 2. \tag{24}$$

Again from (22), setting the coefficients of $tanh^{p-1}\tau$ terms to zero yields

$$-p\lambda v\eta - 2\lambda \eta^{3} p \left[2p^{2} + (p-1)(p-2)\right] - \lambda \eta^{3} b^{2} p \left[2p^{2} + (p-1)(p-2)\right] = 0.$$
⁽²⁵⁾

If we put p = 2 and solving the equation in (25), we obtain

$$v = -8\eta^2 (b^2 + 2). \tag{26}$$

Setting the coefficients of $\tanh^{p+1} \tau$ and $\tanh^{2p-1} \tau$ or $\tanh^{p+3} \tau$ and $\tanh^{2p+1} \tau$ terms in Eq. (22) to zero we get

$$ap\lambda^{2}\eta + p\lambda\nu\eta + 2\lambda p\eta^{3} \left[2p^{2} + (p+1)(p+2)\right] + \lambda p\eta^{3}b^{2} \left[2p^{2} + (p+1)(p+2)\right] = 0.$$
(27)

If we put p = 2 and solving the equation in (27), we get

$$\lambda = -\frac{12\eta^2(b^2 + 2)}{a}, \quad a \neq 0.$$
 (28)

Lastly, we can determine the dark (topological) soliton solution for the Eq. (1) as

$$u(x, y, z, t) = \lambda \tanh^2(\eta (x + y + bz - vt)),$$
⁽²⁹⁾

where the velocity of the solitons v is given in (26), free parameter λ is given by (28).

3 The Drinfeld-Sokolov (DS) system

Let us second consider the Drinfeld-Sokolov system [34]

$$u_t + (v^2)_x = 0, (30)$$

158

$$v_t - av_{xxx} + 3bu_x v + 3huv_x = 0, (31)$$

where a, b and h are real constants. This system was introduced by Drinfeld and Sokolov as an example of a system of nonlinear equations possessing Lax pairs of a special form [35]. Wazwaz [36] used the sine-cosine method and the tanh method to stress the power of these methods to nonlinear equations. Bekir [34] successfully used the extended tanh method and the auxiliary equation method [37] establish solitary wave solutions of the Drinfeld-Sokolov equations. Wazwaz [36] also investigated the traveling wave solutions with compact and noncompact structures for the Drinfeld-Sokolov equations and Qi et al. employ the complex method to obtain the general meromorphic solutions of the Drinfeld-Sokolov equations (DS system of equations) [38].

3.1 Bright (non-topological) soliton solution

In order to seek soliton solutions to (30) and (31), the starting assumptions are

$$u(x,t) = A_1 sech^p \left\{ \eta \left(x - vt \right) \right\}$$
(32)

and

$$v(x,t) = A_2 sech^r \left\{ \eta \left(x - vt \right) \right\}$$
(33)

which A_1, A_2, η and v are constant coefficients. Here A_1, A_2 are the amplitude, η is the inverse width and v is the velocity of the soliton. The exponents p is unknown at this point and will be determined later. From (32) and (33), it is possible to obtain:

$$pA_1\eta vsech^p\tau \tanh\tau - 2rA_2^2\eta sech^{2r}\tau \tanh\tau = 0,$$
(34)

and

$$rA_{2}\eta vsech^{r}\tau \tanh \tau + ar^{3}A_{2}\eta^{3}sech^{r}\tau \tanh \tau$$

$$-r(r+1)(r+2)aA_{2}\eta^{3}sech^{r+2}\tau \tanh \tau$$

$$-3bpA_{1}A_{2}\eta sech^{p+r}\tau \tanh \tau$$

$$-3hrA_{1}A_{2}\eta sech^{p+r}\tau \tanh \tau$$

$$= 0.$$
(35)

Equating the exponents of $sech^{p}\tau \tanh \tau$ and $sech^{2r}\tau \tanh \tau$ terms in Eq. (34), one obtains

$$p = 2r, (36)$$

^{© 2015} BISKA Bilisim Technology



and theirs coefficients gives

$$pA_1\eta v - 2rA_2^2\eta = 0, (37)$$

then we get,

$$v = \frac{A_2^2}{A_1}.$$
 (38)

Similarly, equating the exponents of $sech^{r+2}\tau \tanh \tau$ and $sech^{p+r}\tau \tanh \tau$ terms in Eq. (35), it is possible to obtain

$$p = 2, \tag{39}$$

so that from (36)

$$r = 1. \tag{40}$$

Setting the coefficients of $sech^r \tau \tanh \tau$ terms to zero we get

$$rA_2\eta v + ar^3 A_2\eta^3 = 0. (41)$$

By using (38) and some calculating, we have

$$\eta = \pm \frac{A_2}{r\sqrt{-aA_1}},\tag{42}$$

which gives the inverse width of the soliton. Additionally, it is necessary to have

$$aA_1 < 0. \tag{43}$$

By setting the coefficients of $sech^{p+r}\tau \tanh \tau$ and $sech^{r+2}\tau \tanh \tau$ terms to zero one gets

$$-r(r+1)(r+2)aA_2\eta^3 - 3bpA_1A_2\eta - 3hrA_1A_2\eta = 0,$$
(44)

and using Eqs. (39), (40) and (42) that gives

$$A_1 = \pm \frac{2A_2}{\sqrt{4b+2h}},$$
(45)

which provided that 4b + 2h > 0.

Therefore the 1-soliton solution of the Drinfeld-Sokolov system is given by

$$u(x,t) = A_1 sech^2 \eta \left(x - vt \right), \tag{46}$$

and

$$v(x,t) = A_2 sech\eta \left(x - vt \right), \tag{47}$$

where the soliton velocity, inverse width and amplitude are given by (38), (42) and (45). respectively.



3.2 Dark (topological) soliton solution

For a dark (topological) 1-soliton solution, the starting hypothesis is given by

$$u(x,t) = A_1 \tanh^p \left\{ \eta \left(x - vt \right) \right\},\tag{48}$$

and

$$v(x,t) = A_2 \tanh^r \left\{ \eta \left(x - vt \right) \right\}. \tag{49}$$

Here in (48) and (49), A_1 , A_2 and η are the free parameters for topological solitons and v is the velocity of the soliton. Similar approach like section 2, by using (48) and (49) we get

$$pv\eta A_1\{\tanh^{p+1}\tau - \tanh^{p-1}\tau\} + 2r\eta A_2^2\{\tanh^{2r-1}\tau - \tanh^{2r+1}\tau\} = 0,$$
(50)

and

$$rv\eta A_{2} \{ \tanh^{r+1} \tau - \tanh^{r-1} \tau \} - ar(r-1)(r-2)A_{2}\eta^{3} \{ \tanh^{r-3} \tau - \tanh^{r-1} \tau \} - ar(r+1)(r+2)A_{2}\eta^{3} \{ \tanh^{r+1} \tau - \tanh^{r+3} \tau \}$$
(51)
$$- 2a(\eta r)^{3}A_{2} \{ \tanh^{r+1} \tau - \tanh^{r-1} \tau \} + 3bp\eta A_{1}A_{2} \{ \tanh^{p+r-1} \tau - \tanh^{p+r+1} \tau \} + 3hr\eta A_{1}A_{2} \{ \tanh^{p+r-1} \tau - \tanh^{p+r+1} \tau \}$$

$$= 0.$$

Now from (50), equating the coefficients of 2r + 1 and p + 1 gives

$$2r + 1 = p + 1, (52)$$

so that

$$p = 2r. (53)$$

It need to be noted that the same result is yielded when the exponent 2r - 1 and p - 1 is equated the other. Again from (51) equating the coefficients of p + r - 1 and r + 1 gives

$$p + r - 1 = r + 1, \tag{54}$$

that leads to

$$p = 2. \tag{55}$$

So that from (3.24),

$$r = 1. \tag{56}$$

Setting the coefficients of $\tanh^{p+j} \tau$ and $\tanh^{2r+j} \tau$ in (50), to zero where j = -1, 1 gives

$$pvA_1 - 2r\eta A_2^2 = 0, (57)$$

^{© 2015} BISKA Bilisim Technology



which gives after using (3.26) and (3.27):

$$v = \frac{A_2^2}{A_1}.$$
 (58)

Again from (51), setting the coefficients of $\tanh^{r+3} \tau$ and $\tanh^{p+r+1} \tau$ terms to zero one obtains:

$$ar(r+1)(r+2)A_2\eta^3 - 3bp\eta A_1A_2 - 3hr\eta A_1A_2 = 0,$$
(59)

the latter gives after using (55) and (56):

$$\eta = \pm \sqrt{\frac{A_1(2b+h)}{2a}}.$$
(60)

From (60), it is possible to see that the solitons will exist provided

$$A_1(2b+h)a > 0. (61)$$

Finally, setting the coefficients of $\tanh^{r+1} \tau$ and $\tanh^{p+r-1} \tau$ in (51) to zero gives

$$rvA_2 - ar(r+1)(r+2)A_2\eta^3 - 2a(\eta r)^3A_2 + 3bp\eta A_1A_2 + 3hr\eta A_1A_2 = 0,$$
(62)

this leads to after using (55), (56), (31) and (60):

$$A_2 = \pm A_1 \sqrt{2b+h},\tag{63}$$

which implies that it is necessary to have 2b + h > 0. By inserting (63) in (58), it is possible to recover

$$v = A_1 (2b+h).$$
 (64)

Lastly, the dark (topological) soliton solutions for the Drinfeld-Sokolov system is given by

$$u(x,t) = A_1 \tanh^2 \{ \eta (x - vt) \},$$
(65)

and

$$v(x,t) = A_2 \tanh\left\{\eta\left(x - vt\right)\right\},\tag{66}$$

where the velocity of the solitons *v* is given in (58) or (64), free parameters η and A_2 are given by (60) and (63) respectively. We see from (60) that the free parameter η is dependent on the other free parameter A_1 . Also in (58) the velocity of the soliton *v* is dependent on the free parameters A_1 and A_2 .

4 Conclusions

We have derived the exact bright and dark soliton solutions of the two nonlinear evolution equations namely the Zakharov–Kuznetsov (ZK) equation and the Drinfeld-Sokolov system. This has been realized by using the solitary wave ansatz method. The solitary wave ansatz is used to carry out this derivation. In view of the analysis, we see that the used method is an efficient method of integrability for constructing exact soliton solutions. Conditions for the existence of soliton

BISKA 162

envelopes have also been reported. To our knowledge, these new solutions have not been reported in former literature, they may be of significant importance for the explanation of some special physical phenomena.

References

- [1] Cai, J., Xie, S., Yang, C. Two Loop Soliton Solutions to the Reduced Ostrovsky Equation, Int. Math. Forum 3 (31) (2008) 1529
- [2] Kudryashov, N. A., Seven Common Errors in Finding Exact Solutions of Nonlinear Differential Equations, Commun. Nonlinear Sci. Numerical Simulation, 14 (2009) 3507 9-10
- [3] Ablowitz, M.J., Segur, H., Solitons and inverse scattering transform, SIAM, Philadelphia, (1981)
- [4] Fan, E., Zhang, J., Applications of the Jacobi elliptic function method to special-type nonlinear equations, Phys. Lett. A, 305, (2002) 383-392
- [5] Liu, S., Fu, Z., Liu, S., Zhao, Q., Jacobi elliptic function expansion method and periodic wave solutions of nonlinear wave equations, Phys. Lett. A, 289, (2001) 69-74
- [6] Malfliet, W., Hereman, W., The tanh method. I: Exact solutions of nonlinear evolution and wave equations, Physica Scripta, 54 (1996) 563-568
- [7] Wazwaz, A.M., The tanh method for travelling wave solutions of nonlinear equations, Applied Mathematics and Computation, 154, 3 (2004) 713-723
- [8] El-Wakil, S.A., Abdou, M.A., New exact travelling wave solutions using modified extended tanh-function method, Chaos, Solitons & Fractals, 31, 4, (2007) 840-852
- [9] Wazwaz, A.M, The extended tanh method for new soliton solutions for many forms of the fifth-order KdV equations, Applied Mathematics and Computation, 184, 2 (2007) 1002-1014
- [10] Wang, M.L., Li X., Zhang, J., The $\left(\frac{G'}{G}\right)$ -expansion method and travelling wave solutions of nonlinear evolution equations in mathematical physics, Physics Letters A, 372, 4 (2008) 417-423
- [11] Bekir, A., Application of the $\left(\frac{G'}{G}\right)$ -expansion method for nonlinear evolution equations, Physics Letters A, 372, 19 (2008) 3400-3406
- [12] Fan, E., Zhang H., A note on the homogeneous balance method, Phys. Lett. A, 246, (1998) 403-406
- [13] Wang, M.L., Exact solutions for a compound KdV-Burgers equation, Phys. Lett. A, 213, (1996) 279-287
- [14] Wazwaz, A.M, A sine-cosine method for handling nonlinear wave equations, Mathematical and Computer Modelling, 40, (2004) 499-508
- [15] Bekir, A., New solitons and periodic wave solutions for some nonlinear physical models by using the sine-cosine method, Physica Scripta, 77, 4 (2008) 501-504
- [16] Wazwaz, A.M, The tanh method and the sine-cosine method for solving the KP-MEW equation, International Journal of Computer Mathematics, 82, 2 (2005) 235-246
- [17] Feng, Z. S., The first integral method to study the Burgers-KdV equation, J. Phys. A: Math. Gen. 35 (2002) 343-349
- [18] Taghizadeh, N., Mirzazadeh, M., The first integral method to some complex nonlinear partial differential equations, Journal of Computational and Applied Mathematics, 235, 16 (2011) 4871-4877
- [19] Abdou, M.A., The extended F-expansion method and its application for a class of nonlinear evolution equations, Chaos, Solitons and Fractals, 31 (2007) 95-104
- [20] Zhang, J.L., Wang, M.L., Wang, Y.M., Fang, Z.D., The improved F-expansion method and its applications, Phys. Lett. A, 350, (2006) 103-109
- [21] Biswas, A., 1-soliton solution of the K(m, n) equation with generalized evolution, Phys. Lett. A 372 (2008) 4601-4602
- [22] Triki, H., Wazwaz, A.M., Bright and dark soliton solutions for a K(m,n) equation with t-dependent coefficients. Phys. Lett. A 373, (2009) 2162–2165

^{© 2015} BISKA Bilisim Technology



- [23] Triki, H., Wazwaz, A.M., A one-soliton solution of the ZK(m, n, k) equation with generalized evolution and time-dependent coefficients, Nonlinear Analysis: Real World Applications 12 (2011) 2822–2825
- [24] Triki, H., Wazwaz, A.M., Bright soliton solution to a generalized Burgers–KdV equation with time-dependent coefficients, Applied Mathematics and Computation 217 (2010) 466–471
- [25] E. Infeld, G. Rowlands, Nonlinear waves, solitons and chaos. Cambridge University Press, (1990)
- [26] A.M. Wazwaz, Exact solutions with solitons and periodic structures for the Zakharov–Kuznetsov (ZK) equation and its modified form, Commun. Nonlinear Sci. Numer. Simul. 10 (2005) 597–606
- [27] H. Wu, T. Fan, Nonlinear dispersive ZK(n,n) equations: New compacton solutions and solitary pattern solutions, Applied Mathematics and Computation 187 (2007) 1308–1314
- [28] Krishnan, E.V., Biswas, A., Solutions to the Zakharov-Kuznetsov equation with higher order nonlinearity by mapping and ansatz methods, Physics of Wave Phenomena, 18 4 (2010) 256-261
- [29] Bekir, A., Guner, O., Bright and dark soliton solutions of the (3 + 1)-dimensional generalized Kadomtsev–Petviashvili equation and generalized Benjamin equation, Pramana-J. Phys., 81 2 (2013) 203-214
- [30] A. Biswas, H. Triki, M. Labidi, Bright and Dark Solitons of the Rosenau-Kawahara Equation with Power Law Nonlinearity, Physics of Wave Phenomena 19 1 (2011) 24–29
- [31] Triki, H., Wazwaz, A.M, Dark solitons for a combined potential KdV and Schwarzian KdV equations with t-dependent coefficients and forcing term, Applied Mathematics and Computation, 217 (2011) 8846–8851
- [32] M. Saha, A.K. Sarma, A. Biswas, Dark optical solitons in power law media with time-dependent coefficients, Physics Letters A 373 (2009) 4438–4441
- [33] Bekir, A., Guner, O., Topological (dark) soliton solutions for the Camassa–Holm type equations, Ocean Engineering, 74 (2013) 276–279
- [34] Bekir, A., Applications of the extended tanh method for coupled nonlinear evolution equations, Communications in Nonlinear Science and Numerical Simulation 13 (2008) 1748–1757
- [35] Göktaş, U., Hereman, W., Symbolic computation of conserved densities for systems of nonlinear evolution equations, Journal of Symbolic Computation, 24 5 (1997) 591–621
- [36] Wazwaz AM. Exact and explicit travelling wave solutions for the nonlinear Drinfield–Sokolov system. Commun Nonlinear Sci Num Simulat 11 (2006) 311–325
- [37] Bekir, A., New Exact TravellingWave Solutions for Regularized Long-wave, Phi-Four and Drinfeld-Sokolov Equations, International Journal of Nonlinear Science 6 1 (2008) 46-52
- [38] Zhang, F., Qi, J., Yuan, W., Further Results about Traveling Wave Exact Solutions of the Drinfeld-Sokolov Equations, Journal of Applied Mathematics, 2013 (2013) 523732